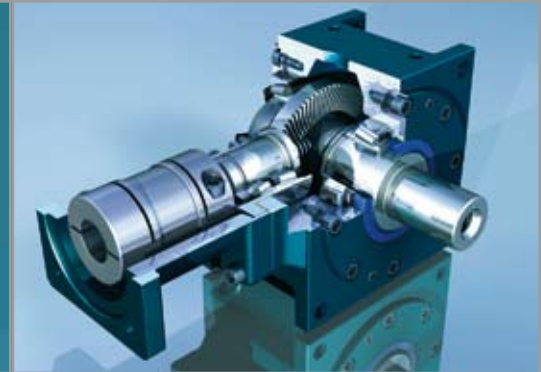
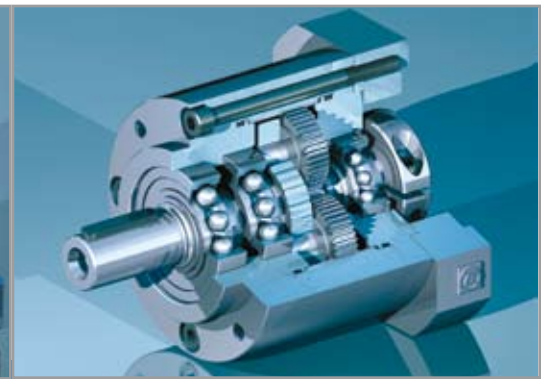
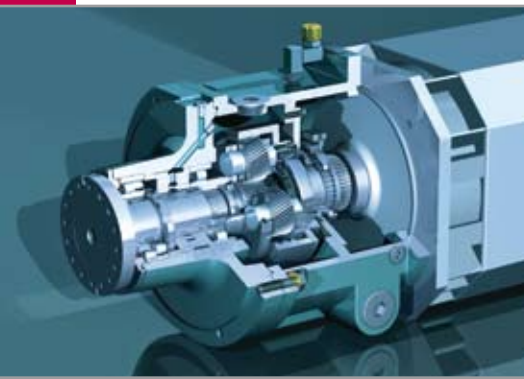




SERVOPLAN®

Precision Worm Gearboxes
for Servomotors



ZF-Duoplan 2K
Two-speed Gearboxes

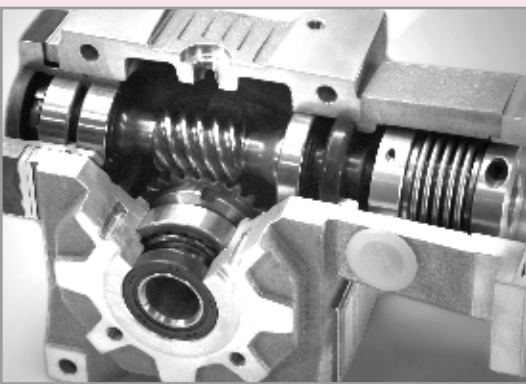
ZF-Servoplan PG
Servogearboxes

ZF-Servoplan PGE
Servogearboxes Economy

ZF-Tiratron
Hysteresis Brakes

Customer specific
Gearboxes

Servoplan WT
Right Angle Gearboxes



Servoplan SWG
Servogearboxes

Precision in movement

Our group has offered its customers a wide range of high quality power transmission components for a long period of time. Our extensive product portfolio includes gearboxes, brakes and clutches serving a variety of industries.

Our geared products include: in-line servo gearboxes (ZF-Servoplan PG and PGE), right angle servo gearboxes (Servoplan WT and Servoplan SWG) serving, among others, the general automation, packaging, material handling, machine tool and robotics industries. Our innovative two-speed gearbox (ZF-Duoplan) was developed for main spindle drives in machine tools.

The innovative line of hysteresis brakes and clutches (ZF-Tiratron) offer non-contact, speed independent torque transmission for web control. Our electromagnetic brakes and clutches have set the standard in a variety of industries for multi disc, friction and toothed versions.

We also offer customer specific gearboxes for a variety of industries including printing and converting, as well as brakes and clutches for industries including exercise equipment, power tool and automotive.



A new step in servogears:

SERVOPLAN SWG

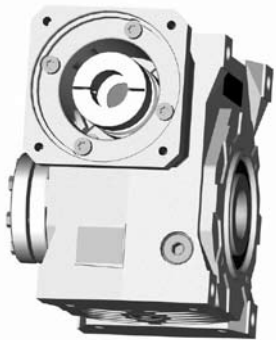
4

3 Precision Levels:

High Precision: backlash ≤ 1 arcmin

Precision: backlash ≤ 3 arcmin

Standard: backlash ≤ 10 arcmin



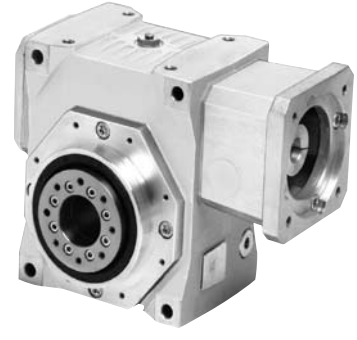
Hollow shaft + servo kit



Dual output shaft + servo kit
(sizes 30-800 only)



Single output shaft + servo kit



Robot flange output
(sizes 80 - 800 only)

1. **Computer optimized gear contact pattern:** less stress, longer life.
2. **Keyless connection:** reliable and backlash free connection with shrink disc.
3. **Servo Adaptation:** including high torsional stiffness coupling with steel bellows coupling + flange available for all existing servomotors.
4. **Oversized taper roller bearings:** provide very high permissible loads.
5. **Constant input bearings preload design:** 2 taper roller bearings + 1 floating ball bearing allowing temperature variations with same preload : higher input permissible speeds, longer life.
6. **Pinned and bound wheel ring:** 100 % stiff and reliable keyless connection, sizes 30-800. Centrifugally cast wheel ring sizes 1500-4800.
7. **Compact design, hardened aluminium-magnesium alloy:** lower weight, higher loads, sizes 30-800. Cast iron sizes 1500-4800.
8. **Life time:** 25000 hours.

SWG benefits

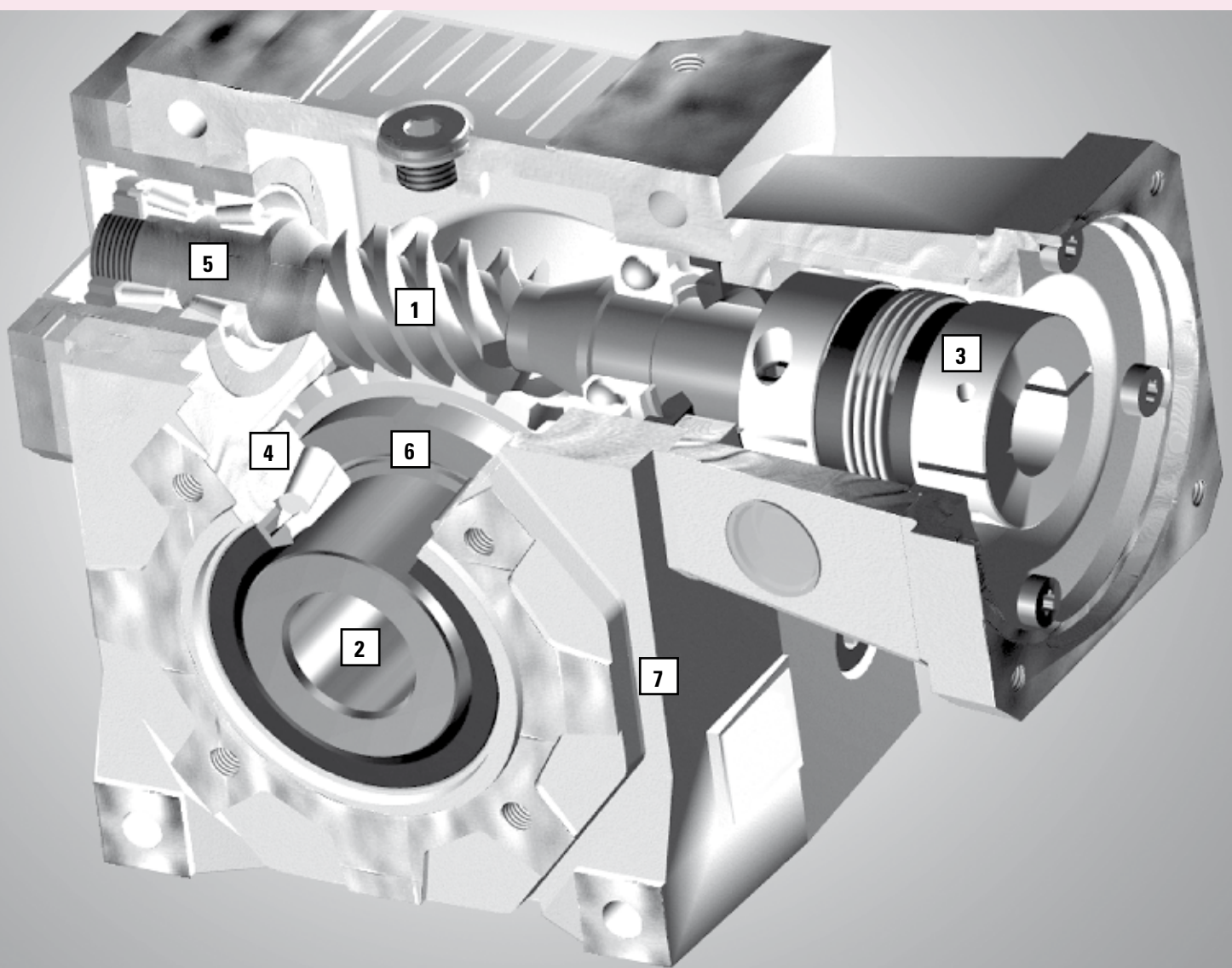
Low backlash

Space saving configuration: the right-angle design, more compact, is favorable in most cases.

Wormgear: low noise level (<55 dB), more important permissible overloads, higher torsional stiffness.

Maintenance free: life-lubricated unit with high performance polyglycol lubricant.

Unbeatable ratio of price to performance



n1		6000			4000			3000			2000			1000			E-stop	C1f	ig	Et	Self Locking	Fr	Fa
i	Torque S5	η	Torque S1	Torque S5	η	Torque S1	Torque S5	η	Torque S1	Torque S5	η	Torque S1	Torque S5	η									
SWG 800	5,2:1	567	96	390	666	95	458	779	95	561	937	94	760	1239	92	2289	2	1,85 X 10 ⁻³	120		21500	16000	
	7,25:1	579	95	417	680	95	488	795	95	599	976	94	802	1307	92	2289	2	1,3 X 10 ⁻³	120		21500	16000	
	10,25:1	650	95	449	786	94	522	878	93	638	1047	92	827	1323	90	2289	2	8,5 X 10 ⁻⁴	120		21500	16000	
	14,5:1	630	93	450	720	92	519	830	91	630	1014	90	810	1247	87	2289	2	6,3 X 10 ⁻⁴	120		21500	16000	
	19,5:1	670	92	510	815	91	589	943	90	705	1121	88	893	1349	85	2289	1	4,6 X 10 ⁻⁴	120		21500	16000	
	30:1	790	88	597	955	87	688	1100	85	812	1299	83	1015	1512	79	2289	1	3,5 X 10 ⁻⁴	120		21500	16000	
	45:1	776	85	583	915	82	665	1037	80	765	1168	78	947	1411	73	2152	1	3 X 10 ⁻⁴	120	✓	21500	16000	
	60:1	683	81	522	815	79	588	905	77	669	1030	73	826	1239	68	2094	0,8	3 X 10 ⁻⁴	120	✓	21500	16000	
	90:1	645	75	497	765	72	557	847	70	625	944	66	778	1128	60	1941	0,8	1,7 X 10 ⁻⁴	120	✓	21500	16000	

n1		6000			4000			3000			2000			1000			E-stop	ig	Self Locking	Fr	Fa	C1f
i	Torque S5	η	Torque S1	Torque S5	η	Torque S1	Torque S5	η	Torque S1	Torque S5	η	Torque S1	Torque S5	η								
SWG 1500	5,125:1	792	97	609	1005	96	716	1181	96	884	1459	95	1217	2008	94	3767	50 X 10 ⁻⁴		13600	12000	2,5	
	7,2:1	840	97	632	1043	96	742	1224	95	907	1497	95	1208	1993	93	3767	38 X 10 ⁻⁴		15000	15000	2,5	
	10,25:1	832	96	622	1026	95	725	1196	95	887	1464	94	1147	1893	92	3767	30,5 X 10 ⁻⁴		16700	18000	2,5	
	15,25:1	726	94	542	894	93	625	1031	92	759	1252	91	972	1604	89	3342	25 X 10 ⁻⁴		18900	22000	2,5	
	20,5:1	1026	93	759	1252	92	877	1447	91	1043	1721	89	1320	2178	87	3767	23,4 X 10 ⁻⁴		20600	22000	1,3	
	29,5:1	869	90	634	1046	88	731	1206	87	861	1421	85	1079	1780	81	3295	23,15 X 10 ⁻⁴		22900	22000	1,3	
	45:1	1142	86	833	1374	84	952	1571	82	1104	1822	80	1369	2259	75	3767	21 X 10 ⁻⁴	✓	26000	22000	1,3	
	60:1	980	82	713	1176	79	815	1345	77	929	1533	74	1150	1898	69	2937	20 X 10 ⁻⁴	✓	28000	22000	1	
	90:1	825	74	598	987	71	680	1122	68	779	1285	64	960	1584	58	2502	19 X 10 ⁻⁴	✓	32000	22000	1	

SWG 2500	5,125:1	1450	97	1128	1861	97	1324	2185	96	1648	2719	96	2334	3851	94	7251	120 X 10 ⁻⁴		17800	15000	3,5
	7,2:1	1411	97	1092	1802	96	1266	2089	96	1569	2589	95	2151	3549	94	7251	77 X 10 ⁻⁴		19700	19000	3,5
	10,25:1	1513	96	1161	1916	96	1346	2221	95	1650	2723	94	2215	3655	93	7251	63 X 10 ⁻⁴		21900	24000	3,5
	15,25:1	1333	95	1030	1700	94	1177	1942	93	1443	2381	92	1896	3128	90	5572	52,7 X 10 ⁻⁴		24700	29000	3,5
	20,5:1	1775	94	1338	2208	93	1530	2525	92	1856	3062	90	2392	3947	88	7251	51,5 X 10 ⁻⁴		27000	34000	1,7
	29,5:1	1492	91	1111	1833	89	1264	2086	88	1535	2533	86	1945	3209	83	6571	52,8 X 10 ⁻⁴		30000	34000	1,7
	45:1	2219	87	1630	2690	85	1858	3066	84	2211	3648	81	2765	4562	77	7251	46,5 X 10 ⁻⁴	✓	34100	34000	1,7
	60:1	1740	83	1272	2099	81	1439	2374	79	1723	2843	76	2127	3510	71	6331	40 X 10 ⁻⁴	✓	37200	34000	1,5
	90:1	1552	76	1123	1853	73	1261	2081	70	1489	2457	67	1842	3039	60	4933	38 X 10 ⁻⁴	✓	42000	34000	1,5

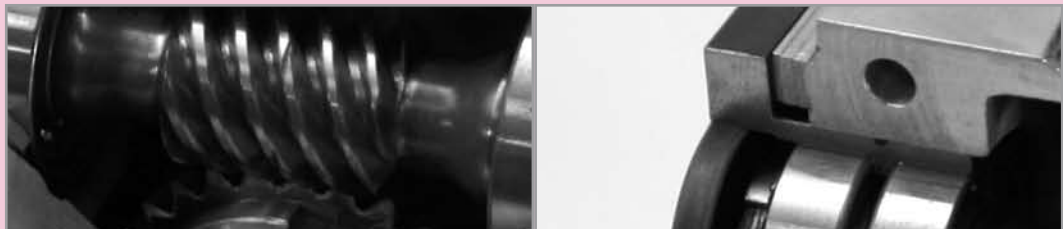
SWG 4800	5,125:1	2592	98	2008	3313	97	2392	3947	97	2954	4874	96	4208	6943	95	12826	287 X 10 ⁻⁴		37000	37500	4,5
	7,2:1	2721	97	2108	3478	97	2462	4062	96	3042	5019	96	4236	6989	94	12826	177 X 10 ⁻⁴		41000	44500	4,5
	10,25:1	2691	97	2071	3417	96	2408	3973	96	2946	4861	95	4007	6612	93	12826	143 X 10 ⁻⁴		46000	52600	4,5
	15,25:1	2346	95	1813	2991	94	2083	3437	94	2540	4191	93	3376	5570	91	12448	102 X 10 ⁻⁴		51800	63000	4,5
	20,5:1	3356	94	2551	4209	93	2909	4800	92	3538	5838	91	4590	7574	89	12826	96 X 10 ⁻⁴		56800	71000	2,2
	29,5:1	2841	92	2117	3493	90	2410	3977	89	2925	4826	87	3738	6168	84	12277	99 X 10 ⁻⁴		63000	71000	2,2
	45:1	3747	88	2775	4579	86	3154	5204	85	3788	6250	83	4747	7833	78	12826	82,5 X 10 ⁻⁴	✓	71700	71000	2,2
	60:1	3170	85	2325	3836	82	2636	4349	80	3159	5212	77	3928	6481	72	11674	71 X 10 ⁻⁴	✓	78000	71000	2
	90:1	2714	78	1985	3275	75	2228	3676	72	2641	4358	69	3316	5471	62	9323	69 X 10 ⁻⁴	✓	88000	71000	2

✓ Denotes self locking feature. However, this feature may be overcome. Therefore, it does not replace a brake.

Notes Concerning Efficiency

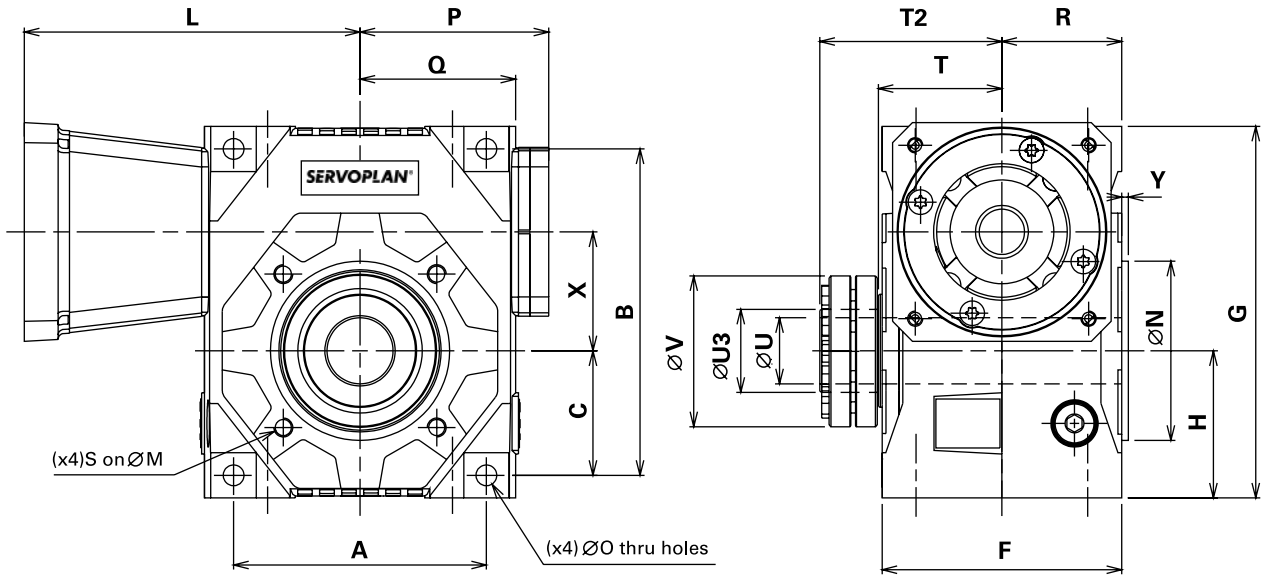
Efficiency values may be achieved after a minimum of 24 hours at full load operation (running-in-period).

Efficiency values are achieved only when gearbox operates at nominal torque. For gearbox operating below nominal torque, efficiency is lower.

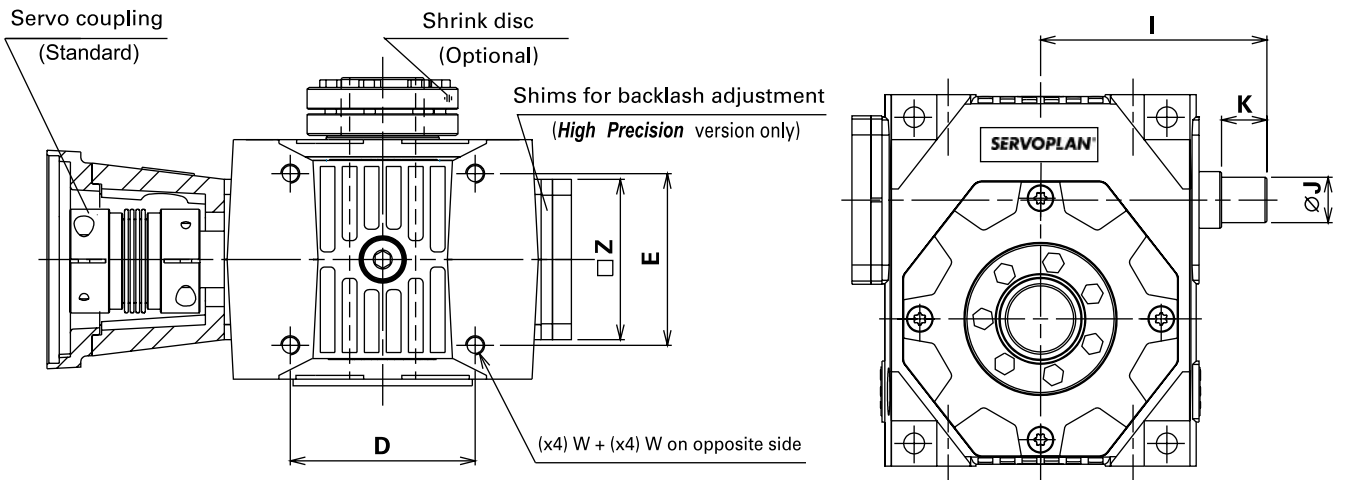


SWG - Hollow Shaft

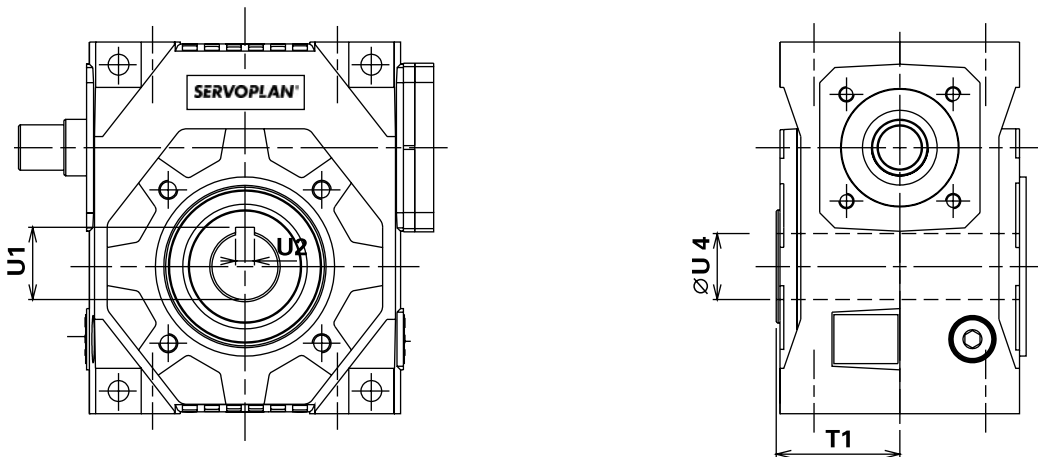
SMOOTH SHAFT FOR SHRINK DISC (AVAILABLE FROM STOCK)



INPUT SHAFT VERSION

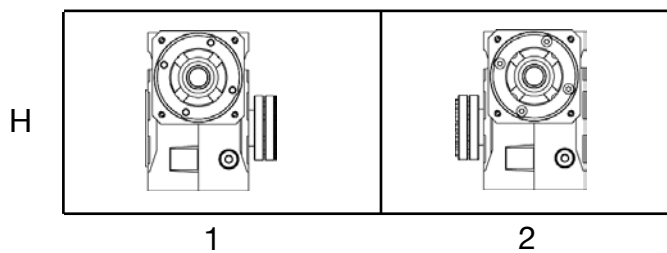


KEYWAYED HOLLOW SHAFT (NOT STOCKED)

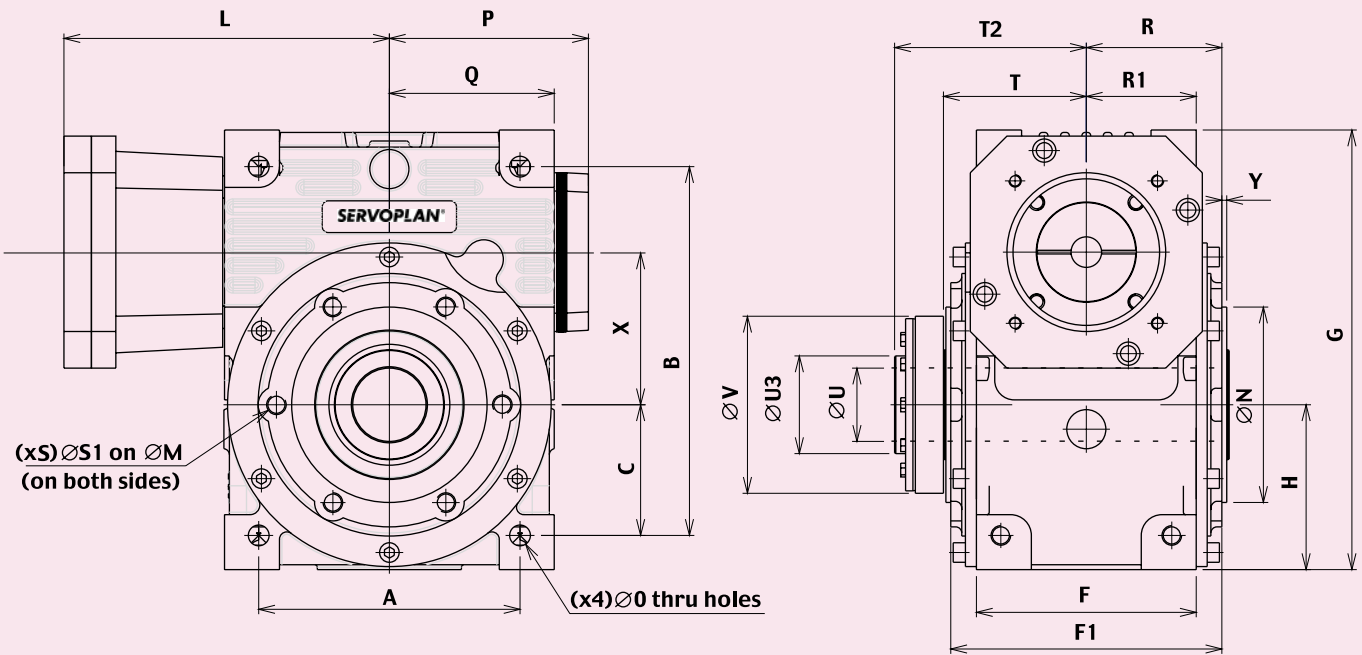


SWG	15	30	80	120	190	260	500	800
A	66	86	108	120	134	172	186	220
B	84	110	135	155	173	208	234	276
C	33	44,5	53	61	66	82	91	108
D	49,5	62	81	90	98	136	141	175
E	44	56	68	78	91	110	130	140
F	64	86	100	112	127	148	170	182
G	96	126	153	175	197	232	264	306
H	39	52,5	62	71	78	94	106	123
I (max)	53	84	105	116	126	151	165,5	189
I (min)	-	77,5	97,5	108	116	140	153,5	177
J (h6)	9	12	15	18	20	24	28	32
K	10	17	20	22	24	28	28	36
L	see page 19							
M	65	65	85	100	115	130	165	200
N (j7)	55	50	70	80	95	110	130	165
O	6,2	7	9	9	11	11	13	13
P (max)	49	70	83,5	91	101	124	136,5	152
Q	42	55	67,5	75	84	104	114,5	132
R	32	43	50	56	63,5	74	85	91
S	M5	M6	M8	M8	M10	M10	M12	M12 (x8)
T	-	45	52	58	65,5	76	87	93
T1	34,5	45	52	58	65,5	76	87	93
T2	-	69	78	87	96,5	110	124	133
U (H7)	-	20	25	30	35	40	50	60
U4	14	16	25	30	35	40	50	60
U1	16,3	18,3	28,3	33,3	38,3	43,3	53,8	64,4
U2	5	5	8	8	10	12	14	18
U3	-	24	30	36	44	50	68	80
V	-	50	60	72	80	90	115	145
W	M5	M6	M8	M8	M10	M10	M12	M12
X	25	35	45	55	63	75	90	110
Y	3	3	3	3,5	3,5	4	4	5
Z	50	58	75	75	85	95	115	115
Weight ca. (kg)	1,4	3,4	6,2	8,5	13,9	20,5	32,5	46,5

Mounting Positions:

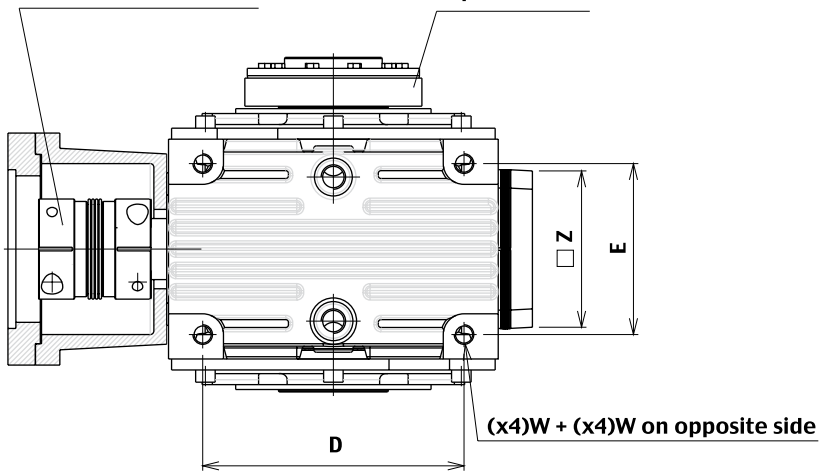


SMOOTH SHAFT FOR SHRINK DISC

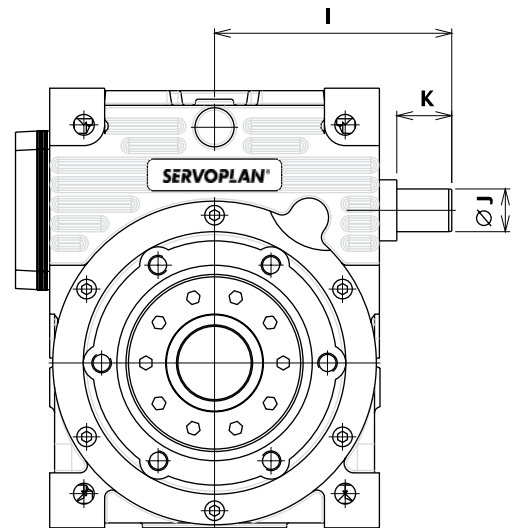


Servo coupling
(Optional)

Shrink disc
(Optional)

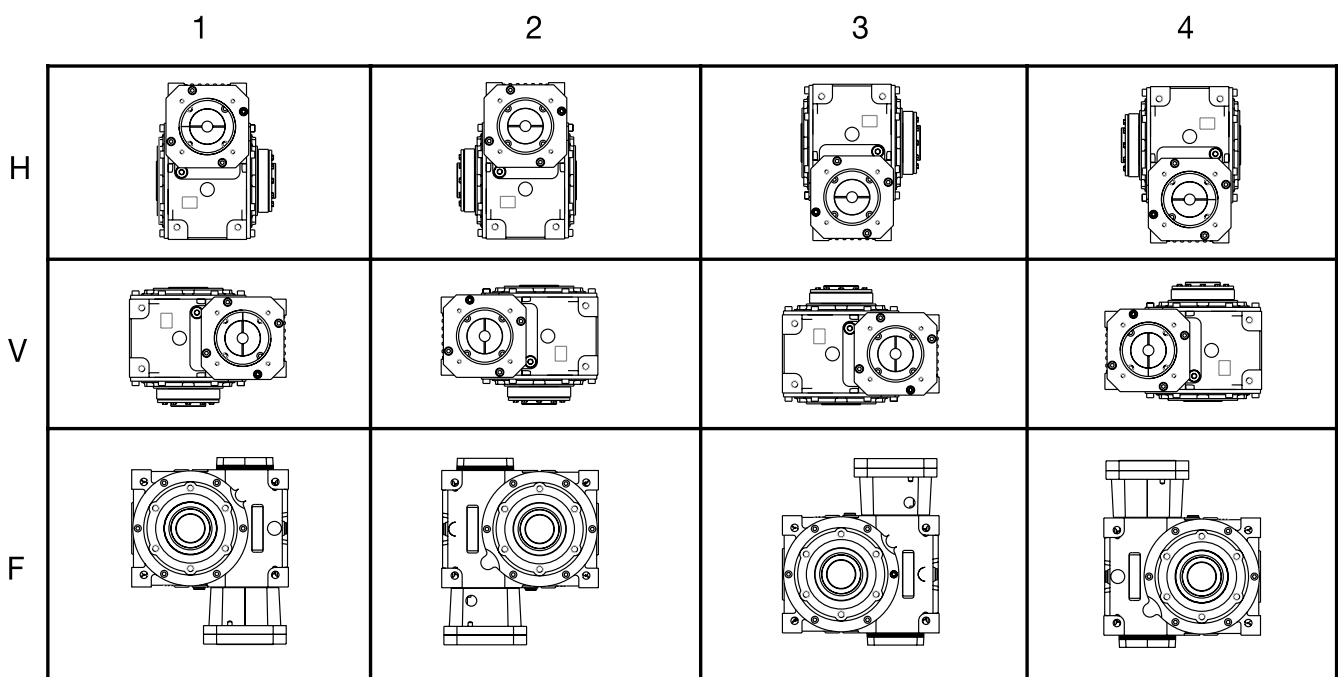


INPUT SHAFT VERSION



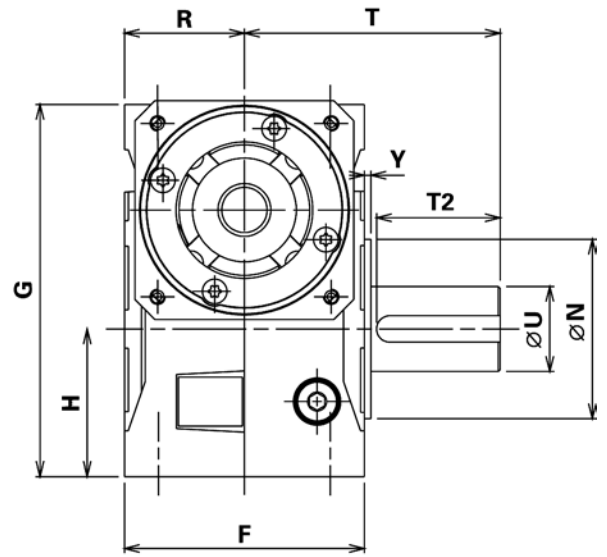
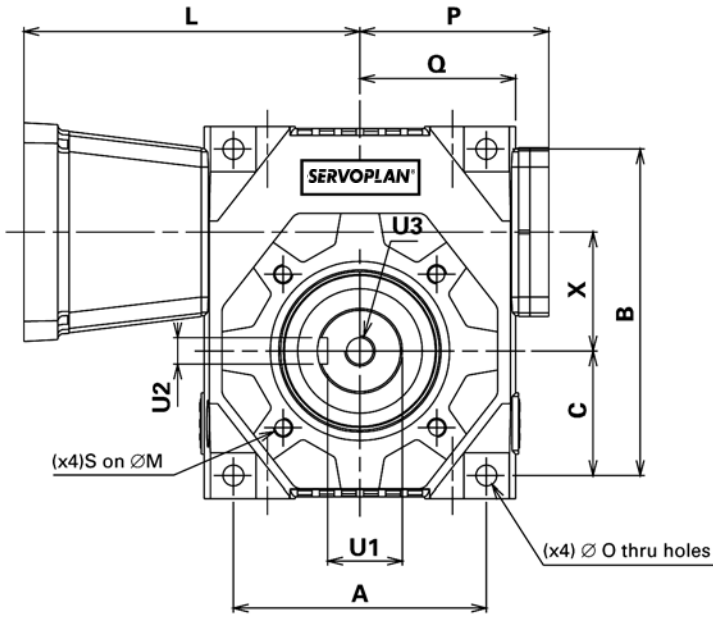
SWG	1500	2500	4800
A	214	284	342,5
B	302	377	483
C	107	142	171
D	214	284	342,5
E	140	150	224
F	180	198	288
F1	222	246	374
G	360	450	576
H	135	175	216
I	195	240	289
J	35	42	48
K	45	50	55
L	see page 21		
M	185	230	300
N	160	190	250
O	17	22	28
P	163	204	251
Q	135	175	216
R	111	123	187
R1	90	99	144
S	6	6	8
S1	M16	M20	M20
T	117	129	194
T2	157	177	264
U	65	75	100
U3	80	90	140
V	145	155	230
W	M16	M20	M20
X	125	160	200
Y	4	5	5
Z	130	140	180
Weight ca. (kg)	108	172	370

Mounting Positions:

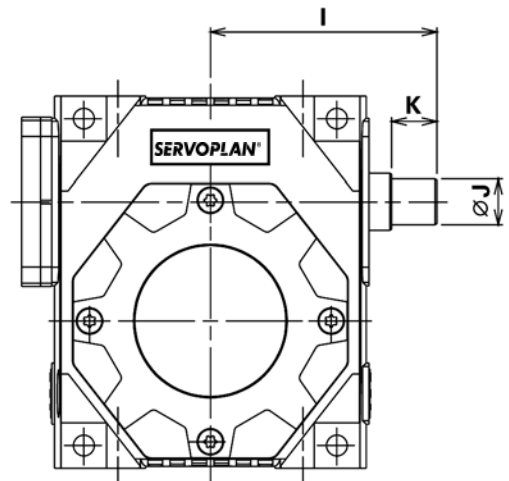
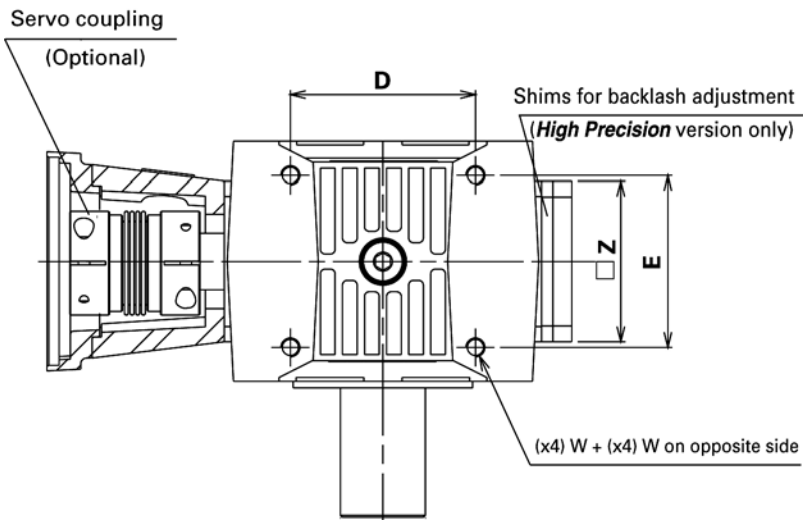


Note: Positions F are shown with shrink disc on back side.

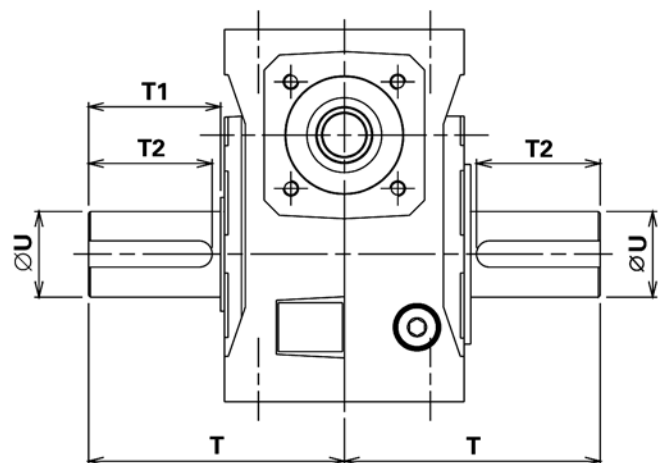
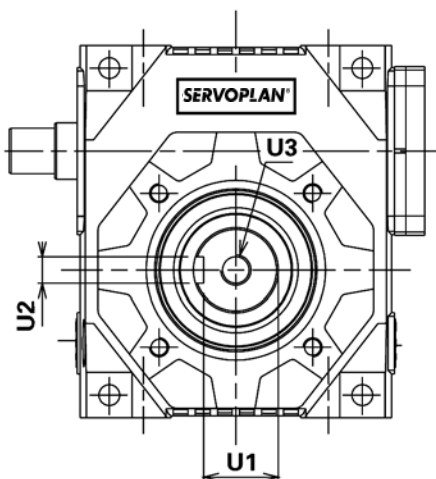
SINGLE OUTPUT SHAFT



INPUT SHAFT VERSION



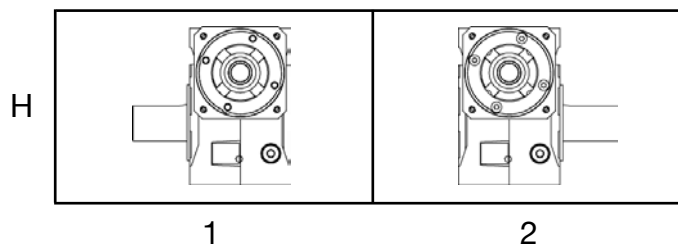
DUAL OUTPUT SHAFT



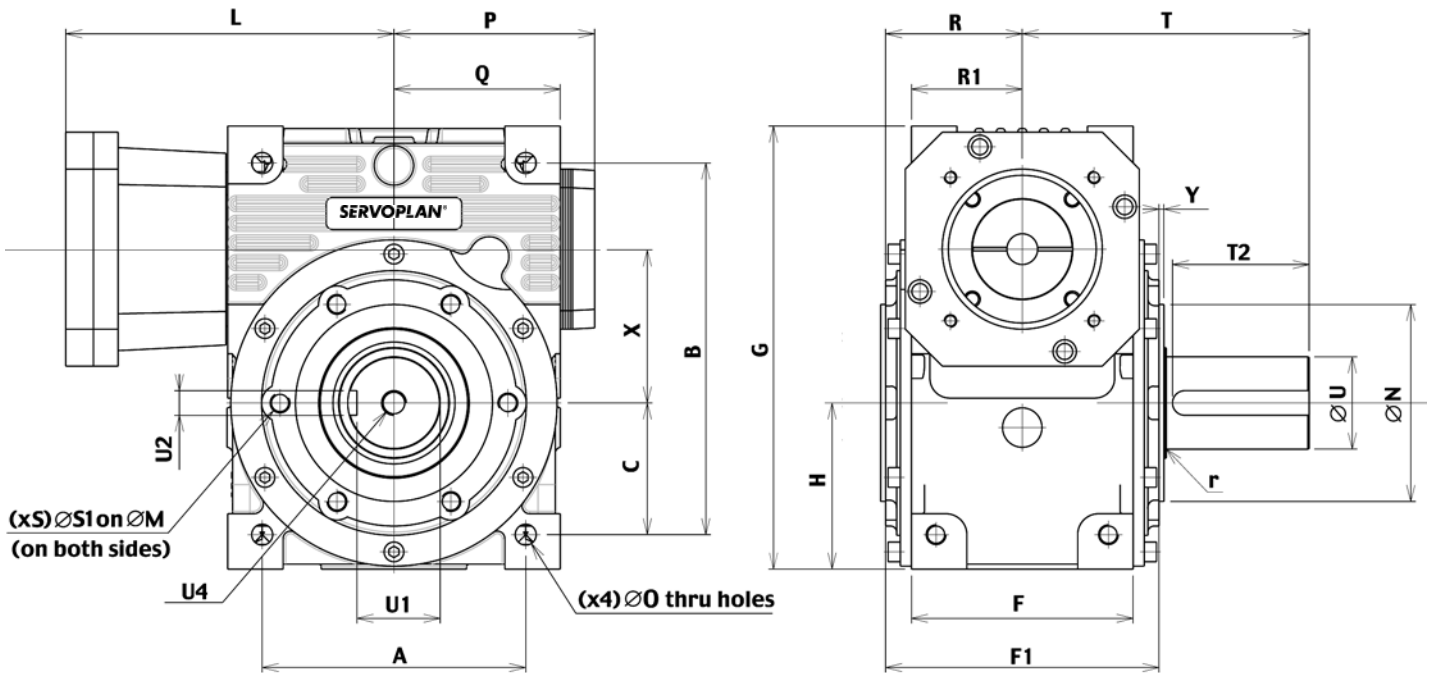
SWG	30	80	120	190	260	500	800
A	86	108	120	134	172	186	220
B	110	135	155	173	208	234	276
C	44,5	53	61	66	82	91	108
D	62	81	90	98	136	141	175
E	56	68	78	91	110	130	140
F	86	100	112	127	148	170	182
G	126	153	175	197	232	264	306
H	52,5	62	71	78	94	106	123
I (max)	84	105	116	126	151	168,5	189
I (min)	77,5	97,5	108	116	140	153,5	177
J (h6)	12	15	18	20	24	28	32
K	17	20	22	24	28	28	36
L	see page 19						
M	65	85	100	115	130	165	200
N (j7)	50	70	80	95	110	130	165
O	7	9	9	11	11	13	13
P (max)	70	83,5	91	101	124	136,5	152
Q	55	67,5	75	84	104	114,5	132
R	43	50	56	63,5	74	85	91
S	M6	M8	M8	M10	M10	M12	M12 (x8)
T	83	107	118	135,5	151	187	208
T1	38*	55*	60*	70	75	100	115
T2	35	50	55	65	70	95,5	110
U (h6)	25	35	40	45	50	65	75
U1	21	30	35	39,5	44,5	58	67,5
U2	8	10	12	14	14	18	20
U3	M10	M12	M16	M16	M16	M20	M20
W	M6	M8	M8	M10	M10	M12	M12
X	35	45	55	63	75	90	110
Y	3	3	3,5	3,5	4	4	5
Z	58	75	75	85	95	115	115
WEIGHT ca. (kg)	3.6	6.8	9.2	15.2	22.2	35.1	50.3

* no shaft shoulder

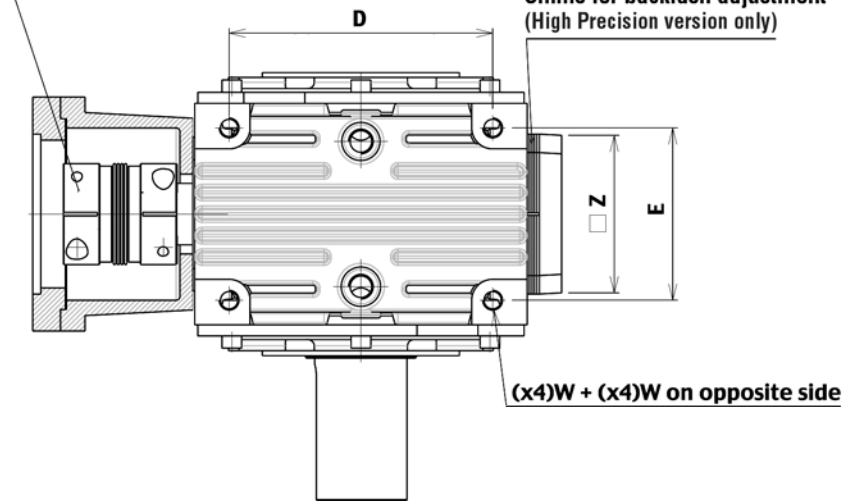
Mounting Positions:



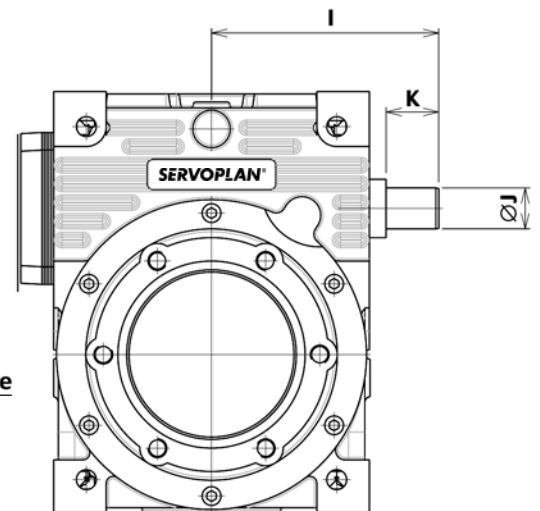
SINGLE OUTPUT SHAFT



Servo coupling (optional)

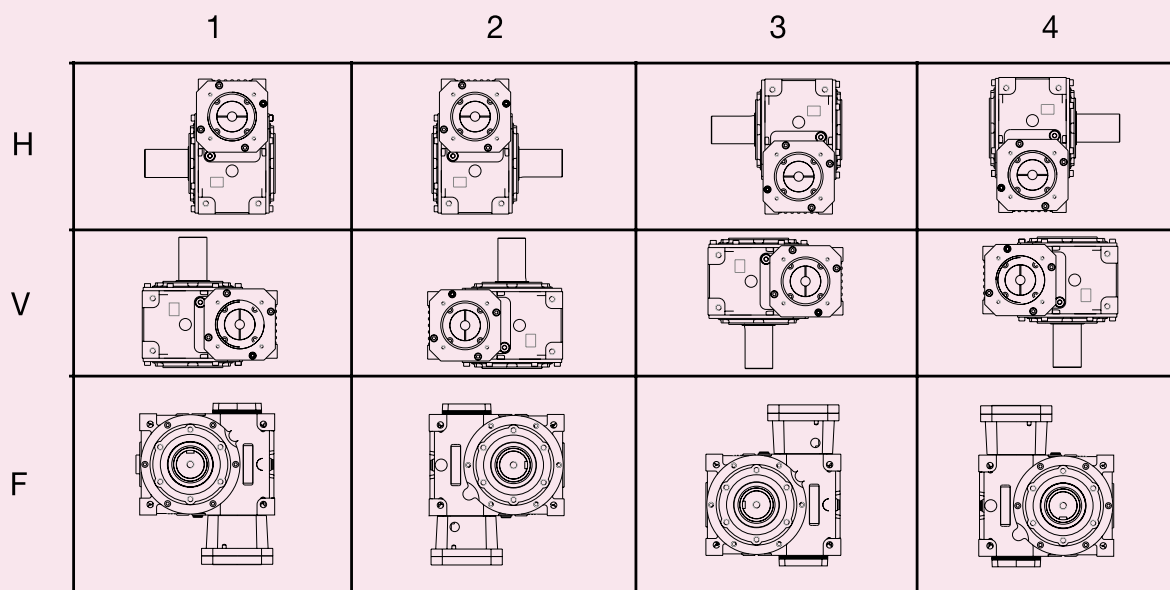


INPUT SHAFT VERSION



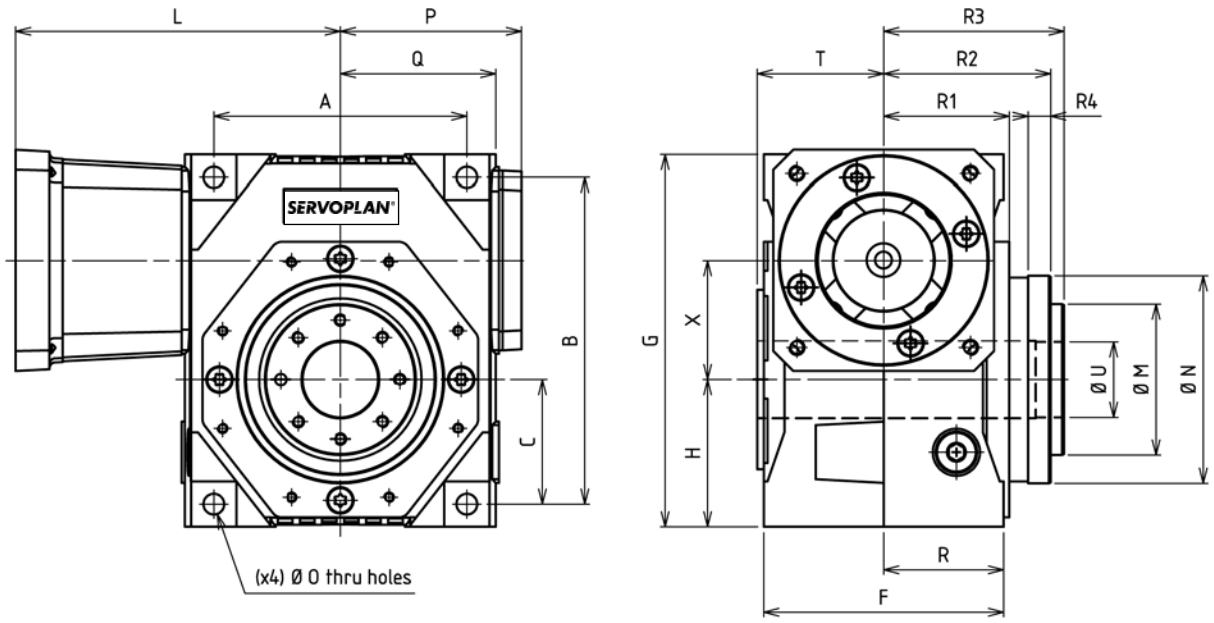
SWG	1500	2500	4800
A	214	284	342,5
B	302	377	483
C	107	142	171
D	214	284	342,5
E	140	150	224
F	180	198	288
F1	222	246	374
G	360	450	576
H	135	175	216
I	195	240	289
J	35	42	48
K	45	50	55
L	see page 21		
M	185	230	300
N	160	190	250
O	17	22	28
P	163	204	251
Q	135	175	216
r	3	3	5
R	111	123	187
R1	90	99	144
S	6	6	8
S1	M16	M20	M20
T	233	269	359
T2	111	135	164
U	75	90	120
U1	67,5	81	109
U2	20	25	32
U4	M20	M24	M24
W	M16	M20	M20
X	125	160	200
Y	4	5	5
Z	130	140	180
WEIGHT ca. (kg)	116	184	400

Mounting Positions:

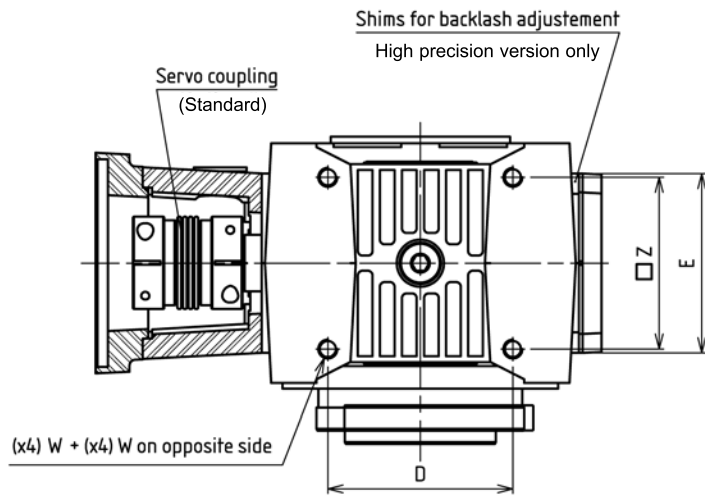


Note: Positions F are shown with shrink disc on back side.

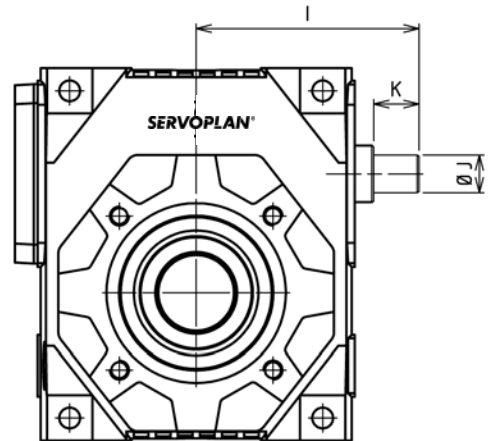
SWG - Robot Flange



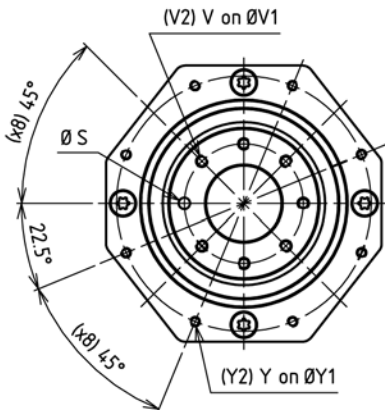
(x4) Ø 0 thru holes



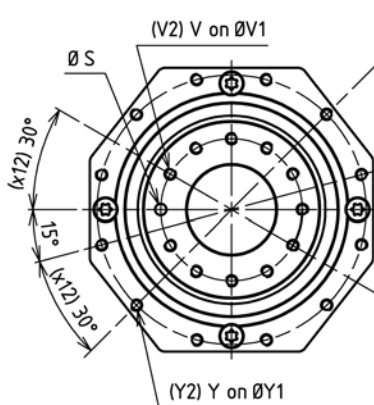
INPUT SHAFT VERSION



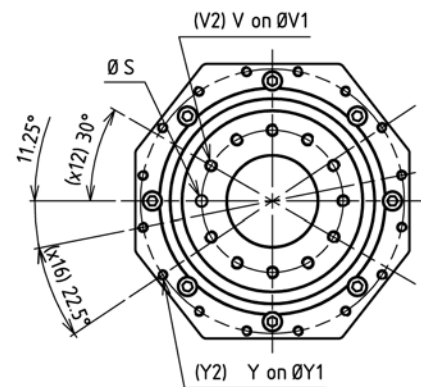
SIZES 80-120 and 190



SIZES 260 and 500

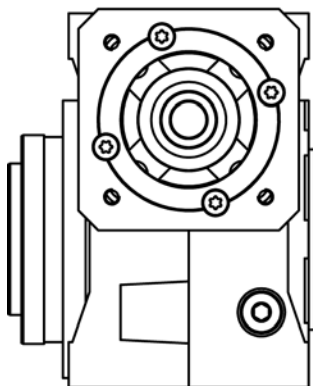


SIZE 800

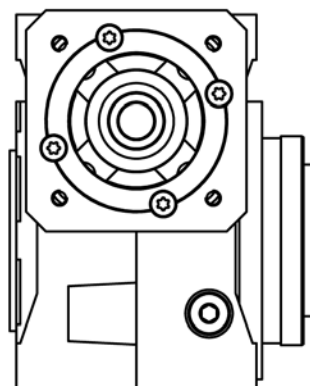


SWG Robot	80	120	190	260	500	800
A	108	120	134	172	186	220
B	135	155	173	208	234	276
C	53	61	66	82	91	108
D	81	90	98	136	141	175
E	68	78	91	110	130	140
F	100	112	127	148	170	182
G	153	175	197	232	264	306
H	62	71	78	94	106	123
I (max)	105	116	126	151	165,5	189
I (min)	97,5	108	116	140	153,5	177
J (h6)	15	18	20	24	28	32
K	20	22	24	28	28	36
L	see page 19					
M (h7)	50	63	80	100	125	160
N (h7)	80	90	110	140	165	200
O	9	9	11	11	13	13
P (max)	83,5	91	101	124	136,5	152
Q	67,5	75	84	104	114,5	132
R	50	56	63,5	74	85	91
R1	54	59	66,5	79	93	100
R2	74	82	88,5	110	129	140
R3	80	89	95,5	117	138	150
R4	10	12	12	15	18	22
S (H7)	6	6	6	8	8	10
T	53	59,5	67	78	89	96
U (H7)	25	31,5	40	50	63	80
V	M6	M6	M6	M8	M8	M10
V1	40	50	63	80	100	125
V2	7	7	7	11	11	11
W	M8	M8	M10	M10	M12	M12
X	45	55	63	75	90	110
Y	M5	M5	M5	M6	M8	M8
Y1	100	109	135	168	190	233
Y2	8	8	8	12	12	16
Z	75	75	85	95	115	115
Weight ca. (kg)	7,5	10,5	15,2	22,5	36,15	51,7
Max. tilting torque (Nm)	250	450	780	1200	2150	3900
Tilting rigidity (Nm/armin)	330	520	580	800	1550	3050

H2

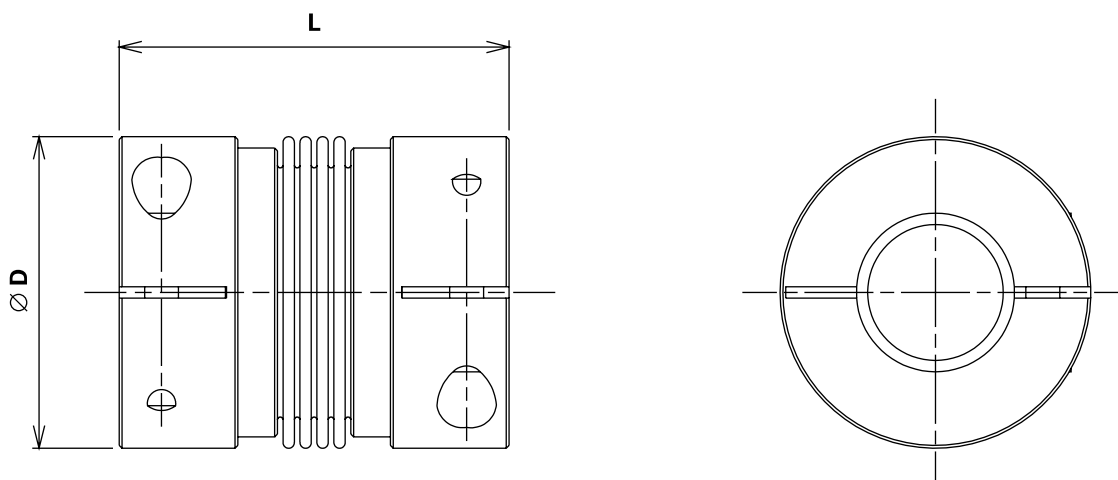


H1



Mounting Positions:

Servo Coupling



Coupling reference		005	010	015	030	060	080
Max. \varnothing servo shaft and SWG shaft	mm	\varnothing 16	\varnothing 24	\varnothing 28	\varnothing 32	\varnothing 35	\varnothing 42
Servo nominal torque	Nm	5	10	15	30	60	80
Servo peak torque	Nm	7.5	15	22.5	45	90	120
\varnothing D	mm	32	40	49	55	66	82
L	mm	42	46	60	70	81	94
Moment of inertia	10^{-3} kgm ²	0.01	0.02	0.05	0.09	0.18	0.54
Torsional stiffness	Nm/arcmin	2	2.6	6	11	22	37
Tightening torque of campling screws	Nm	4	4.5	9	14	35	70

Specify the coupling reference and the motor shaft \varnothing when ordering.

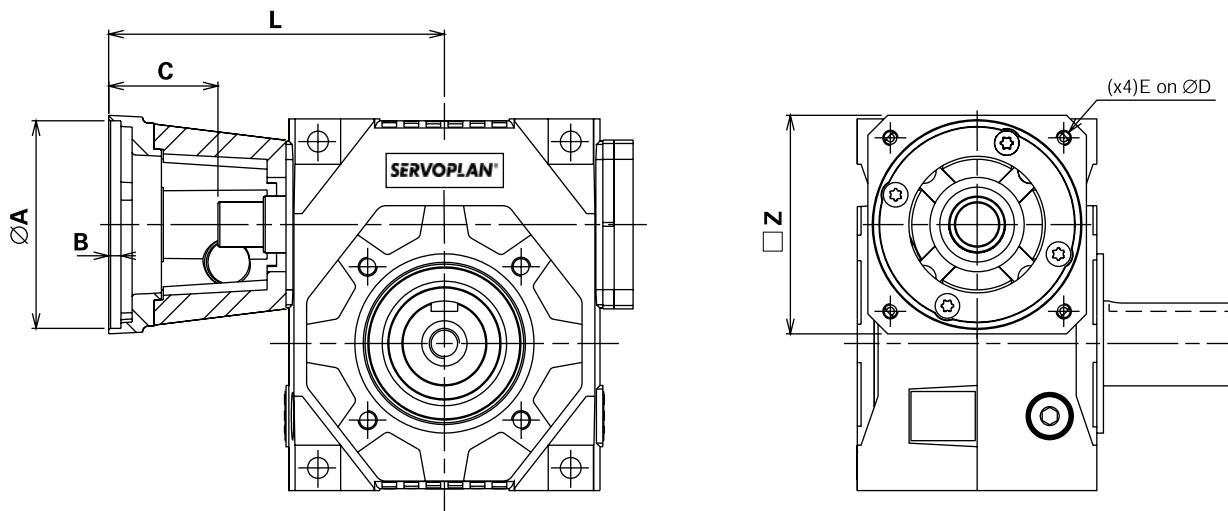
Example: couplingsize 015 \varnothing 14

To calculate the total input inertia, add the coupling inertia to the gearbox inertia (page 6).

Servo Flange

Select the required flange on page 19.

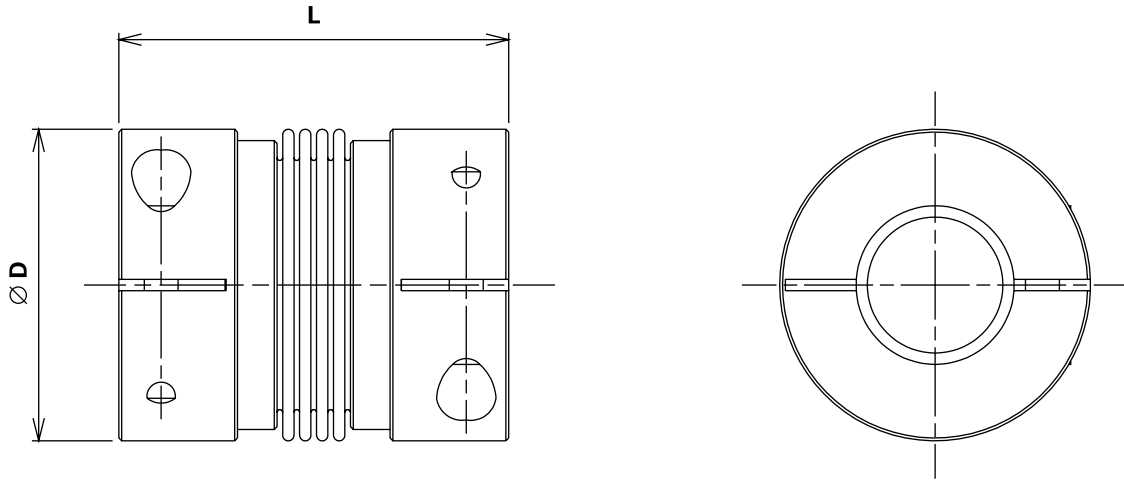
If no flange can be found in the list, supply the dimensions from A to Z, or supply the servo reference when ordering as in page 19 + 21 shown



SWG	Reference	A	B	C max*1	D	E	L*1	Z
15	AA	30	4	27	46	M3	80	58
	AB	40	4	27	63	M4	80	65
	AC	50	4	32	70	M4	85	65
	AE	60	4	32	75	M5	85	65
	AF	70	4	32	90	M5	85	90
	AG	50	4	32	95	M6	85	90
	AH	80	5	42	100	M6	95	90
	AI	95	5	52	115	M8	105	105
30	AA	40	4	32	63	M4	111	65
	AB	50	4	35	70	M4	114	65
	AC	60	4	35	75	M5	114	65
	AD	70	4	45	90	M5	124	90
	AE	50	4	35	95	M6	114	90
	AF	80	4	45	100	M6	124	90
	AG	95	5	45	115	M8	124	118
	AH	95	5	55	130	M8	134	118
	AI	110	5	55	130	M8	134	118
	AJ	110	6,5	65	145	M8	144	118
	AA	50	4	35	70	M4	135	81
	AB	60	4	35	75	M5	135	81
	AC	70	4	45	90	M5	145	91
	AD	50	4	35	95	M6	135	91
	AE	80	5	45	100	M6	145	91
	AF	95	5	45	115	M8	145	115
	AG	95	5	55	130	M8	155	115
	AH	110	5	55	130	M8	155	115
	AI	110	6,5	65	145	M8	165	140
	AJ	110	6,5	55	165	M10	155	140
	AK	130	6,5	55	165	M10	155	140
	AA	50	4	35	70	M4	146	81
	AB	60	4	35	75	M5	146	81
	AC	70	4	45	90	M5	156	91
	AD	50	4	35	95	M6	146	91
	AE	80	4	45	100	M6	156	91
	AF	95	5	45	115	M8	156	115
	AG	95	5	55	130	M8	166	115
	AH	110	5	55	130	M8	166	115
	AI	110	6,5	65	145	M8	176	140
	AJ	110	6,5	55	165	M10	166	140
	AK	130	6,5	55	165	M10	166	140
120	AA	50	4	40	70	M4	160	102
	AB	60	4	40	75	M5	160	102
	AC	70	4	46	90	M5	166	102
	AD	80	5	46	100	M6	166	102
	AE	95	5	46	115	M8	166	115
	AF	95	5	56	130	M8	176	115
	AG	110	5	56	130	M8	176	115
	AH	110	6,5	66	145	M8	186	140
	AI	110	6,5	56	165	M10	176	140
	AJ	130	6,5	56	165	M10	176	140
	AK	114,3	6,5	86	200	M10	206	185
	AL	130	6,5	66	215	M12	186	185
	AM	180	6,5	66	215	M12	186	185
	AA	50	4	40	70	M4	185	102
	AB	60	4	40	75	M5	185	102
	AC	70	4	46	90	M5	191	102
	AD	80	5	46	100	M6	191	102
	AE	95	5	46	115	M8	191	115
	AF	95	5	56	130	M8	201	115
	AG	110	5	56	130	M8	201	115
	AH	110	6,5	66	145	M8	211	140
	AI	110	6,5	56	165	M10	201	140
	AJ	130	6,5	56	165	M10	201	140
	AK	114,3	6,5	86	200	M10	231	185
	AL	130	6,5	66	215	M12	211	185
	AM	180	6,5	66	215	M12	211	185
	AA	80	4	46	100	M6	205,5	123
	AB	95	5	46	115	M8	205,5	123
	AC	95	5	56	130	M8	215,5	123
	AD	110	5	56	130	M8	215,5	123
	AE	110	6,5	66	145	M8	225,5	140
	AF	110	6,5	56	165	M10	215,5	140
	AG	130	6,5	56	165	M10	215,5	140
	AH	114,3	6,5	86	200	M10	245,5	185
	AI	130	6,5	66	215	M12	225,5	185
	AJ	180	6,5	66	215	M12	225,5	185
	AK	250	6,5	88	300	M14	247,5	260

*1 If length of motorshaft is longer than C min, a intermediale ring according to order number system (page 23) has to be defined to compensale the overlength. In this case L will be longer accordingly.

Servo Coupling



Coupling reference		060	080	150	300	500
Max. Ø servo shaft and SWG shaft	mm	Ø 35	Ø 42	Ø 42	Ø 60	Ø 62
Servo nominal torque	Nm	60	80	150	300	500
Servo peak torque	Nm	90	120	225	450	750
Ø D	mm	66	82	82	110	123
L	mm	79	92	92	109	114
Moment of inertia	10 ⁻³ kgm ²	0.18	0.54	0.65	2.68	9
Torsional stiffness	Nm/arcmin	21	23	41	46	85
Tightening torque of clamping screws	Nm	35	60	75	120	200

Specify the coupling reference and the motor shaft when ordering.

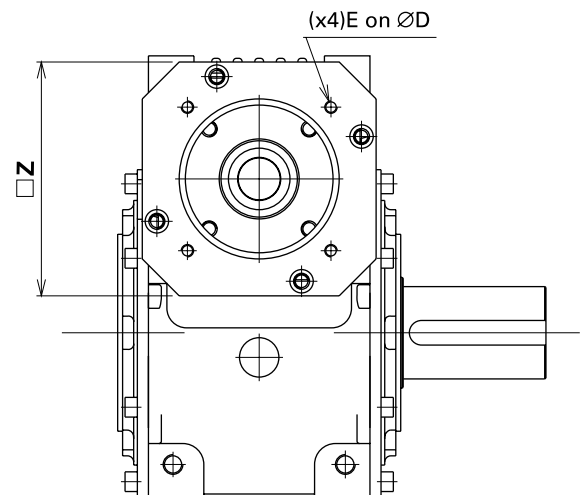
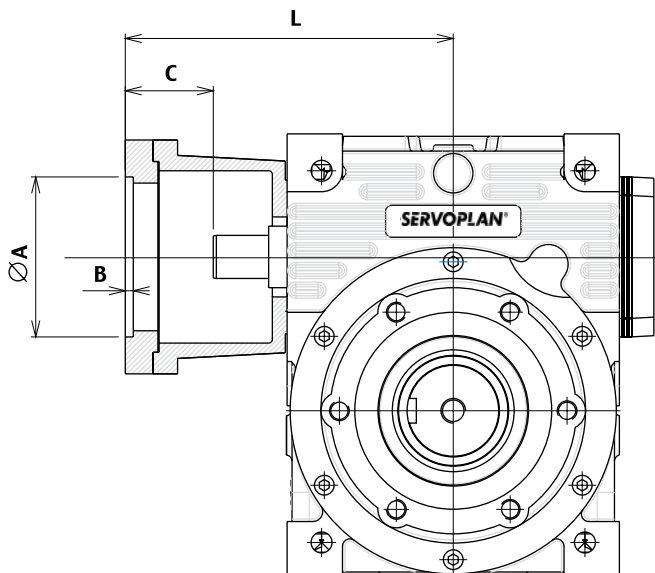
Example: couplingsize 150 Ø 42

To calculate the total input inertia, add the coupling inertia to the gearbox inertia (page 6 and 7).

Servo Flange

Select the required flange on page 19.

If no flange can be found in the list, supply the dimensions from A to Z, or supply the servo reference when ordering as in page 19 and 21 shown



SWG	Reference	A	B	C min*1	D	E	L*1	Z	
800	AA	80	4	46	100	M6	229	123	
	AB	95	5	46	115	M8	229	123	
	AC	95	5	56	130	M8	239	123	
	AD	110	5	56	130	M8	239	123	
	AE	110	6,5	66	145	M8	249	140	
	AF	110	6,5	56	165	M10	239	140	
	AG	130	6,5	56	165	M10	239	140	
	AH	114,3	6,5	86	200	M10	269	185	
	AI	130	6,5	66	215	M12	249	185	
	AJ	180	6,5	66	215	M12	249	185	
	AK	250	6,5	88	300	M14	271	260	
	1500	AA	95	5	42	115	M8	247	190
		AR	95	5	52	130	M8	257	190
AC		110	5	52	130	M8	257	190	
AD		110	6,5	62	145	M8	267	190	
AE		110	6,5	52	165	M10	257	190	
AF		130	6,5	52	165	M10	257	190	
AG		114,3	6,5	82	200	M10	287	190	
AH		130	6,5	62	215	M12	267	190	
AI		180	6,5	62	215	M12	267	190	
AJ		230	6,5	85	265	M12	290	260	
AK		250	6,5	85	300	M14	290	260	
AL		300	8,5	112	350	M16	317	360	
2500		AA	130	6,5	52	165	M10	321	200
	AB	114,3	6,5	82	200	M10	351	200	
	AC	130	6,5	62	215	M12	331	200	
	AD	180	6,5	62	215	M12	331	200	
	AE	230	6,5	85	265	M12	331	260	
	AF	250	6,5	85	300	M14	354	260	
	AG	300	8,5	112	350	M16	381	360	
	4800	AA	130	6,5	52	165	M10	365	200
AB		114,3	6,5	82	200	M10	399	200	
AC		130	6,5	62	215	M12	379	200	
AD		180	6,5	62	215	M12	379	200	
AE		230	6,5	85	265	M12	402	260	
AF		250	6,5	85	300	M14	402	260	
AG		300	8,5	112	350	M16	429	360	
AH		350	10,5	142	400	M16	460	420	

*1 If length of motorshaft is longer than C max, a intermediale ring according to order number system (page 23) has to be defined to compensate the overlength. In this case L will be longer accordingly.

Start/Stop Service S5

- Calculate acceleration torque on gearbox output:-

$$C2acc = C1acc \times i \times \eta \times F1 \times F2$$



F1 and **F2**:- correction factors as per following chart.

GEARBOX RUNNING TIME DURING 1 FULL CYCLE					
	10 %	30 %	50 %	70 %	90 %
F1	0.7	0.85	1	1.11	1.2

NUMBER OF STARTS PER HOUR				
	1000 to 2000	2000 to 3000	3000 to 5000	5000 to 10000
F2	1 to 1.35	1.35 to 1.45	1.45 to 1.6	1.6 to 1.9

Intermediates values

To be interpolated



- Select the gearbox size in the column **Torque S5** :



$$\text{Torque S5} > C2acc$$

Continuous Service S1

- Calculate nominal torque on gearbox output

$$C2nom = C1nom \times i \times \eta$$



- Select the gearbox size in the column **Torque S1** :



$$\text{Torque S1} > C2nom$$

LEGEND

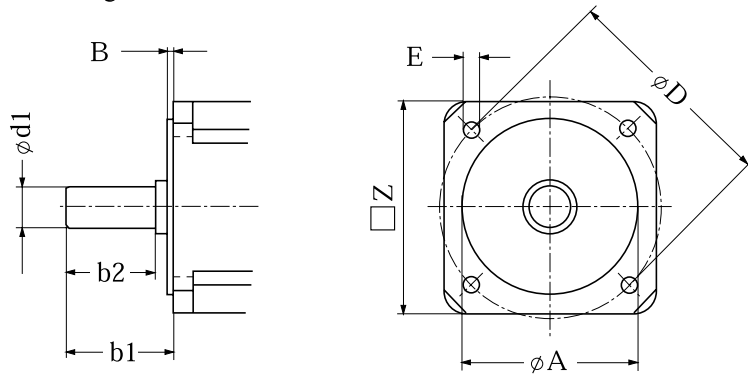
- $C1acc$ (Nm) : motor acceleration torque
- $C1nom$ (Nm) : nominal motor torque
- $C2acc$ (Nm) : gearbox output acceleration torque
- $C2nom$ (Nm) : Gearbox output nominal torque
- $E-stop$ (Nm) : gearbox output emergency torque (2 seconds duration maximum, applied a maximum of 25000 times over the gearbox life)
- $C1f$ (Nm) : starting input friction torque (without any load on output)
- $N1$: maximum input RPM to be achieved during a full cycle (S5 service) or input nominal RPM (S1 service)
- i : exact gear ratio
- Et (Nm/arcmin) : Torsional stiffness on output
- ig (kgm²) : moment of inertia on input (to be added to coupling inertia, see page 10)
- η (%) : gearbox efficiency at considered input RPM
- Fr (N) : permissible radial load on output shaft (applied at the middle of the shaft)
- Fa (N) : permissible axial load on output shaft

Quotation Request:

Kindly fill out below questionnaire for speedy processing and send to:

Fax: ++49 (0) 40 53540024 or ++49 (0) 154691847

E-Mail: marzahl@marzahl.de or info@automation-and-gears.de



Motor data:

Motor manufacturer: _____

Type: _____

Motor shaft diameter d1 [mm]: _____

Flange face distance b1 [mm]: _____

Motor shaft length b2 [mm]: _____

Centering diameter A [mm]: _____

Fixing hole circle diameter D [mm]: _____

Fixing hole diameter E [mm]: _____

Flange square □Z [mm]: _____

Motor nominal torque [Nm]: _____

Motor maximum torque [Nm]: _____

Fa (N) max permissible axial force on the outputshaft: _____



Gearbox data:

Servoplan size: _____

SWG-

Servoplan ratio [i]: _____

Keyed output shaft (yes/no): _____

Backlash specification (high Precision, Precision or Standard): _____

Ordering number (see below): _____

Basis of quotation (batch size): _____

Projected annual volume: _____



Subject to technical change without notice. For studies,

please request installation drawings; only the data contained therein is binding.

S W G 0 8 0 0 A 9 0 H 1 H 1 A E 0 3 0 - 1 9

Motor shaft \varnothing mm

Coupling reference (page 18/20)

Motor flange code (page 19/21)

Installation (page 9,11,13,15 and 17)

Size	15	30	80	120	190	260	500	800	1500	2500	4800
1	0	0	0	0	0	0	0	0	0	0	0
2	-	-	11	11	20	20	20	20	20	-	-
3	-	-	-	-	30	30	30	30	-	-	-

intermediate Ring for extendet motorshaft

N	Hollow shaft, no shrink disc
R	Robot flange
H	Hollow shaft including shrink disc
K	Hollow shaft with keyway
S	Single output shaft
D	Dual output shaft

Output Options

Code	05	07	10	15	20	30	45	60	90
Ratio	5.2	7.25	10.25	14.5	19.5	30	45	60	90

Backlash

A	High precision 1 arcmin
B	Precision 3 arcmin
C	Standard 10 arcmin

Code	0015	0030	0080	0120	0190	0260	0500	0800	1500	2500	4800
Size	15	30	80	120	190	260	500	800	1500	2500	4800

Example

S W G 0 8 0 0 A 9 0 H 1 H 1 A E 0 3 0 - 1 9



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